

# Hiking Powered Prosthetic Foot By Team Tyr Sponsored by Quality of Life Plus

Dr. Scott Shaffer, SDSU | Dr. Barry Dorr, SDSU | Annemarie Orr, QL+ | Nick Kimmel, U.S. Marine Corps

#### **Project Overview**

#### Problem Statement:

The project description is to design a powered hiking prosthetic foot solution for Quality of Life Plus, a national organization that aims to improve the lives of disabled veterans and first responders. Our team was challenged to design an advanced prosthetic capable of going on long hiking and hunting expeditions in inclement weather.

#### Need:

This project is designed to assist Nick Kimmel, a Marine who sustained injuries in duty leading to amputation of both legs above the knee and one arm above the elbow. The prosthetic device shall provide powered assistance to one leg for going up and down hills so that Nick can engage in his usual physical activities.

#### **Team Members**

#### ME:



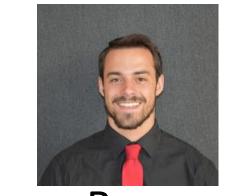
Mathew Blake ME Team Lead



**Garrett Grommes** Design Engineer



Susana Arellano Design Engineer

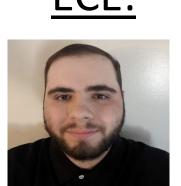


Zachary Brueggeman Manufacturing Engineer



Marc Anthony Do Quality/Test Engineer

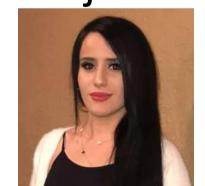
ECE:



Justin Killam **ECE Team Lead** 



Nassar Almarshoud EE Project Lead



Dina Bastros Safety Engineer

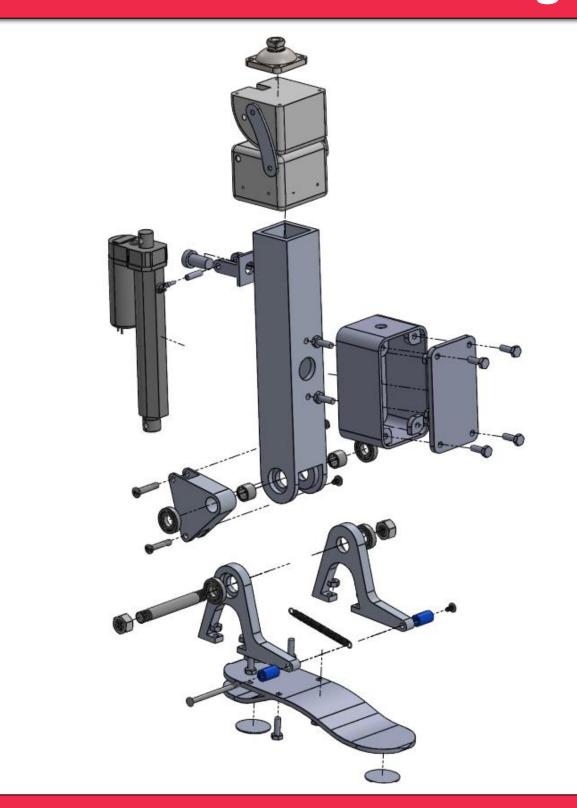


Jarel-Johnson Macanas Design Engineer



Sony Shosani Design Engineer

### **Mechanical Design**



**Electrical Design** 

LM7808\_T0220

Fiberglass Flex Foot Subassembly

SHIELD-MD10\_R2

A2 11 A3 12 SDA/A4 13 SCL/A5 14

Elegoo\_UNO\_R3

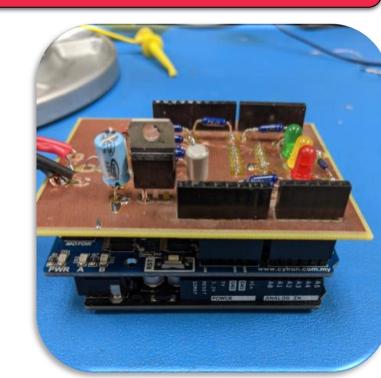
₹ R? 51.1K

1 + Actuator1 S12-09A08-04-CAA

### **Final Product**

Assembled System With Electronic Housing





Assembled and Soldered Boards

# **Prototyping**

- Initial prototype tested with a bypass (right).
- First iteration of molded fiberglass foot (below).







## **Design Analysis**

Major structural parts simulated under 250 lbs. of loading to account for the weight of the user and any additional gear they may carry.

Pylon:

## **Testing**

₹ R? 51.1K

₹ R? 9.2k

≷ R? 820

R? 1.87k

₹ R? 37.9k

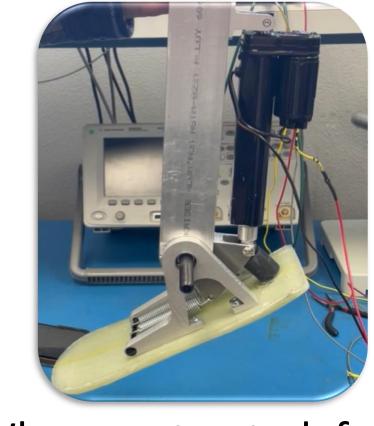
Testing the system's range of motion with the extension of the actuator and its location on the pylon.

Complete Electronics

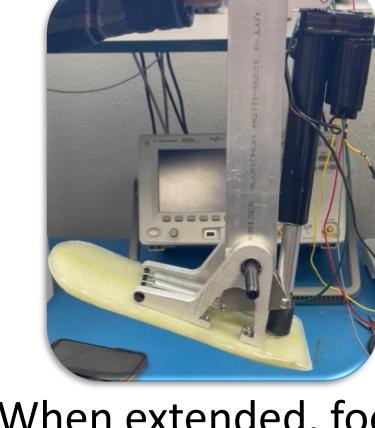
Schematic Diagram

(right)

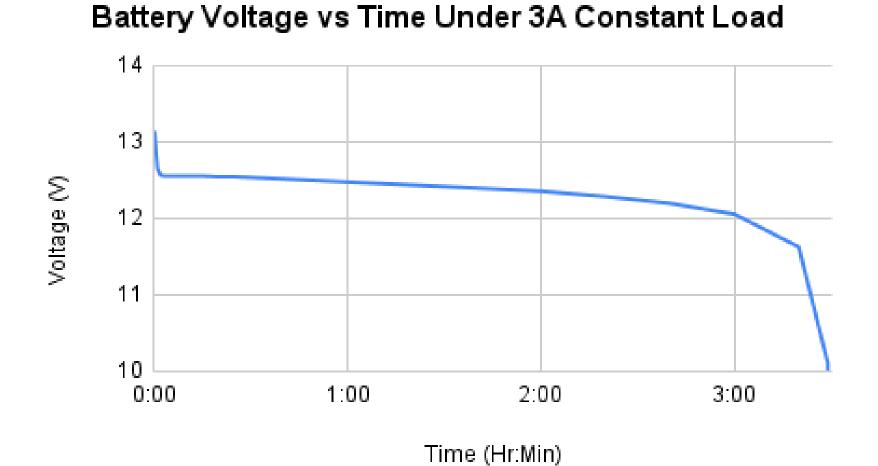
PCB Design V.1 (below)



When contracted, foot is in plantar flexion.

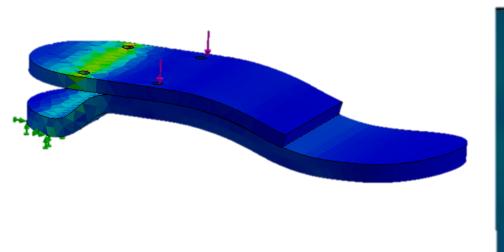


When extended, foot is in dorsiflexion.

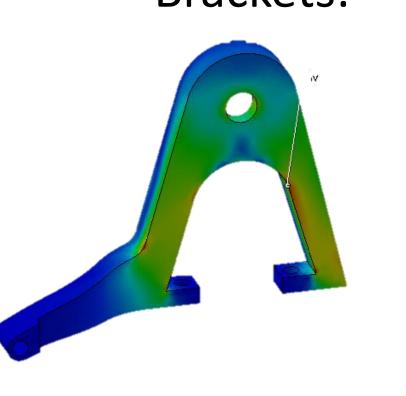


Testing the system's battery under a 3A constant load, we found the battery lasted approximately 3 hours, sufficient for the average length hike.

Foot Assembly:



**Brackets:** 



All were under yield strength and showed no serious deformation.

