

Project Overview

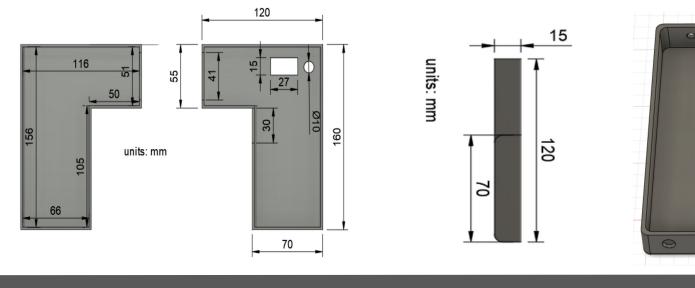
The Automatic Guitar Tuner is a smart, motorized device that will aid musicians and music enthusiasts alike in tuning their guitars accurately and efficiently. The primary motivation behind this project was to expand our knowledge and experience with audio signal processing. Our product is connected to an electric guitar via auxiliary cable. When a string is played, the device determines its pitch and compares this to a pre-programmed reference (i.e., the desired value). It then turns the motor (affixed to a tuning peg) the correct amount in order to bring the string to the desired pitch.

Key Specifications

- Standard-E tuning The system is only designed to tune a guitar to standard-E (E,A,D,G,B,e = 82, 110, 147, 196, 247, 330) Hz.
- Ergonomic design "Gun-shaped" to comfortably fit user's hand.
- Microcontroller ESP32 with 240 MHz clock, 600 MIPS, 32-bit registers, and 12-bit ADC.
- Trigger-operated motor Continuous servo controlled by PWM signals from ESP32.
- Universal nozzle Designed to fit any tuning peg.
- String-select button Cycle through strings.
- Input power 9VDC @ 500mA (max), regulated from 120V mains.

Enclosure Manufacturing Process

Designed in Fusion360, our enclosure is 3D printed using PLA filaments.





Somer Hanna CompE Major



Matthew Hughes EE + ME Major



Meet The Team

Ara Jacob EE Major



Eric Taft CompE Major

Automatic Guitar Tuner

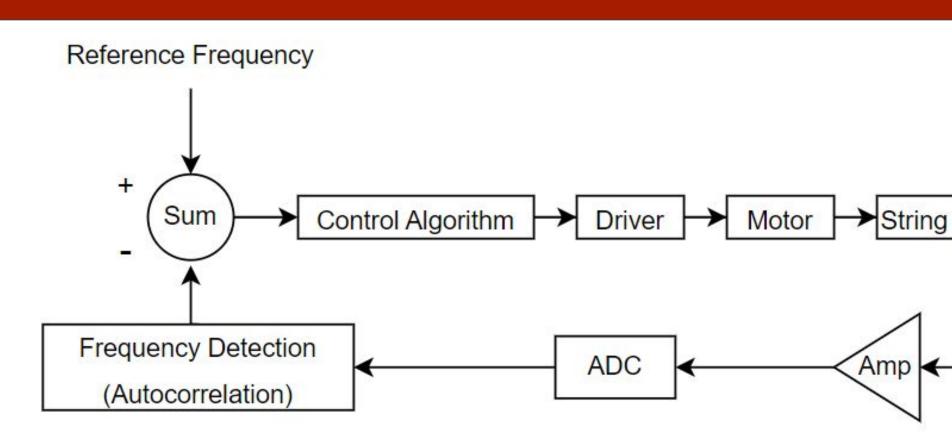
Block Diagram







AJ Rodrigo CompE Major



Key Technologies

Developed:

- Frequency detection algorithm (autocorrelation).
- **Tuning algorithm to control direction and duration of motor** rotations.

Procured:

- **ESP32** microcontroller.
- Continuous servo motor (30 kgcm torque).
- **OLED** display.

Signal Processing Firmware

Autocorrelation Algorithm:

Input signal is sampled over a small time interval at t=0. 2. A copy of sample is incrementally compared with original signal, being shifted one sample each time. 3. A 'correlation' value is assigned to each comparison, indicating the similarity between sampled and original signals with respect to the amount of time shifted.

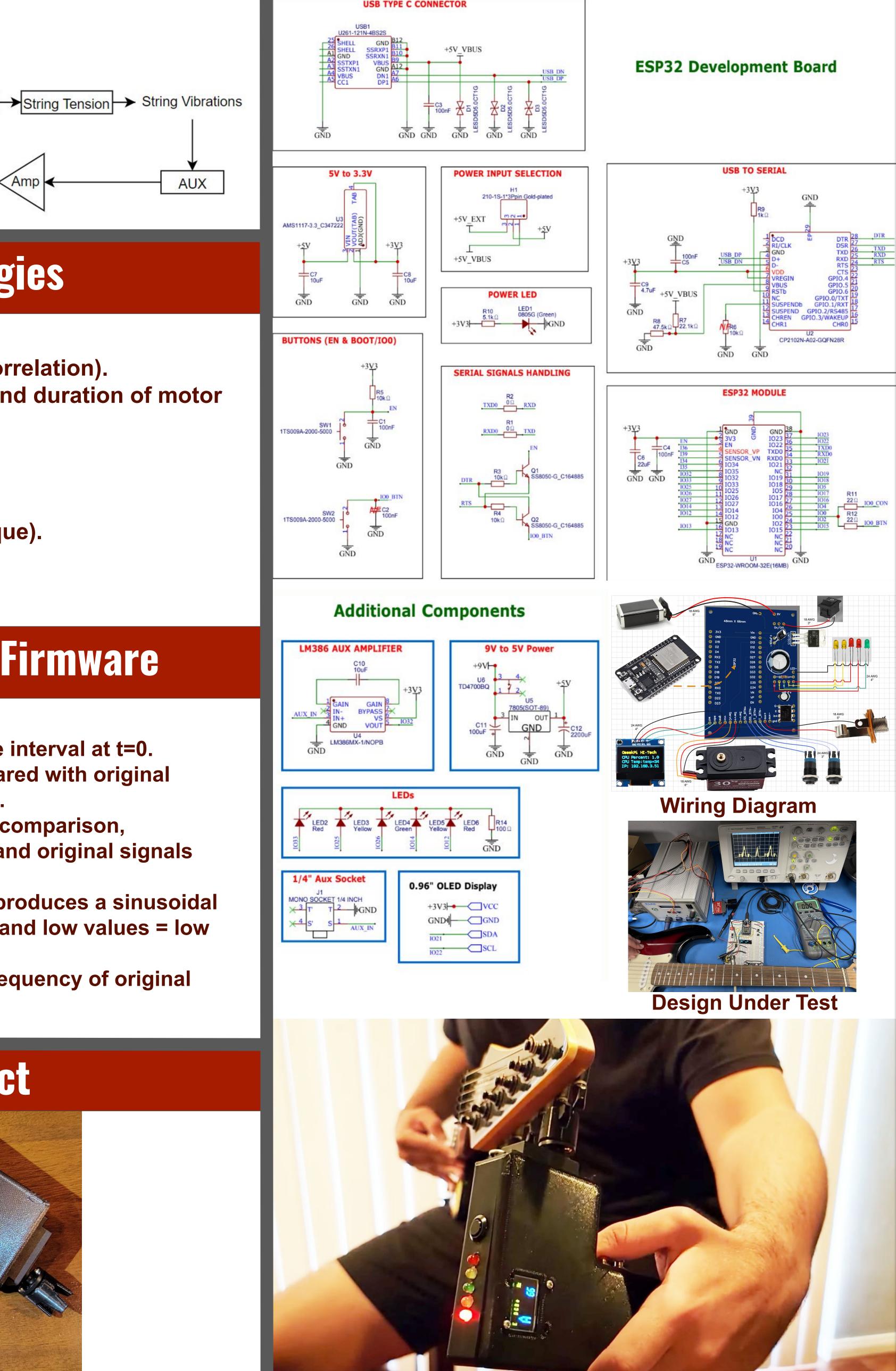
4. Plotting correlation values against time produces a sinusoidal trace where high values = high correlation and low values = low correlation.

5. Frequency of this trace = fundamental frequency of original signal.

Final Product



San Diego State SDSU University Hardware **ESP32 Development Board** 210-1S-1*3Ppin Gold-plated 4.7uF +5V_VBUS **POWER LED** RXD0 00 TXD GND 2



Spring 2023

Product In Use