



Project Overview and Motivation

The Robotic Palm Tree Trimmer is a remote controlled robot designed to climb palm trees in order to cut dead fronds. The purpose of this project is to reduce injuries and fatal accidents during palm tree trimming. This is a continuation project going on its third year of improvement. This year, the focus is a redesign of the upper stage platform, track, and the traction arms. As well as to address issues of climbing and moving the circumferential platform around the track.

Meet the Sponsor

Max Marek Winiarz is a retired engineer and founder of Max Engineering, an entity dedicated to pursuing innovative engineering projects driven by passion and purpose. One of his key initiatives is the development of a robotic palm trimmer with the vision of saving lives by enhancing the safety and efficiency of palm tree maintenance, also helping towards the prevention of wildfires.



Max Marek Winiarz
Project Sponsor

Meet Team Mechatronics



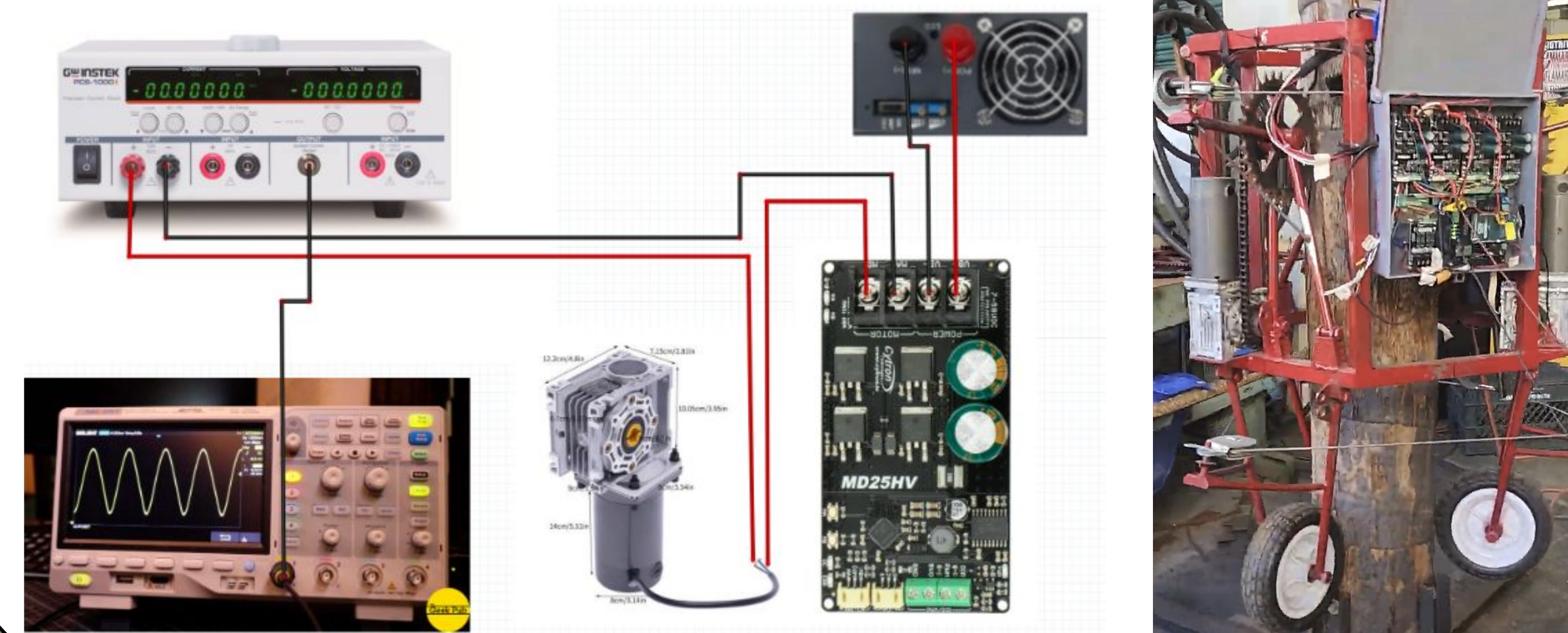
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|----------------------------------------|---------------------------------------------|-------------------------------------------------------|-------------------------------------------------|----------------------------------------------|
| Alyssa De La Torre
Team Lead | Lukas Hruza
Lead CAD Engineer | Christian Montano
Manufacturing Engineer | Andres Santos
ME Quality Engineer | Esha Ram
Safety Engineer |
| Daniel Cueva
ECE Lead | Kanji Hirayama
Lead Test Engineer | Coltin Haniotakis
Wiring Logistics Engineer | Nicolas Armenta
Machine Code Engineer | Kevin Lee
Controller Code Engineer |

Conclusion

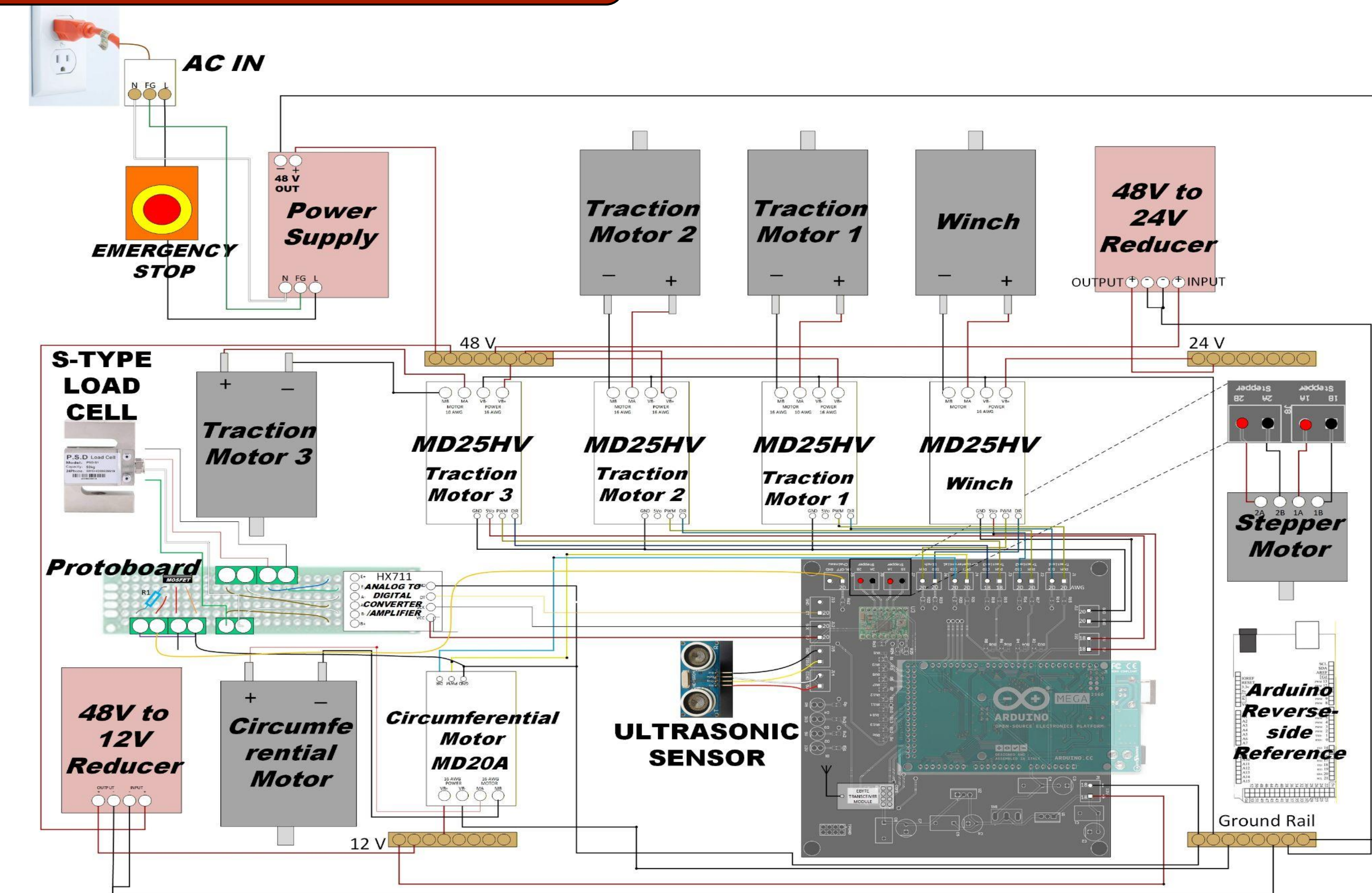
Over the course of this project, the upper stage and traction arms were redesigned. Additionally, key power issues were diagnosed and handled mechanically by improving the gear ratio rather than seeking a new power supply. The inconsistent behaviour of the wireless controller (previously a bare PCB) has been resolved with a newly designed and 3D printed case.

Testing and Verification

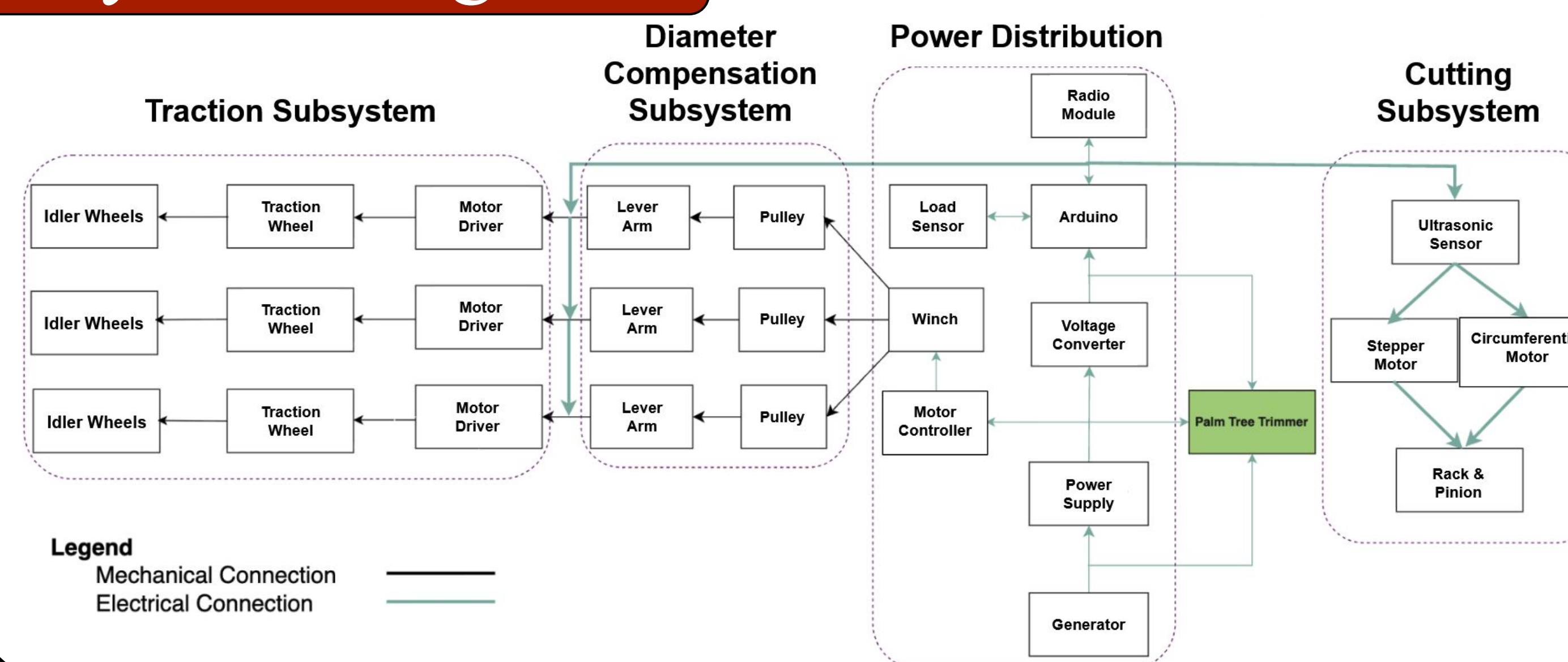
Electrical testing was performed to get voltage and current traces from the motors to formulate a better understanding as to why the machine was not climbing. Necessary component wiring and a climbing test can be seen below.



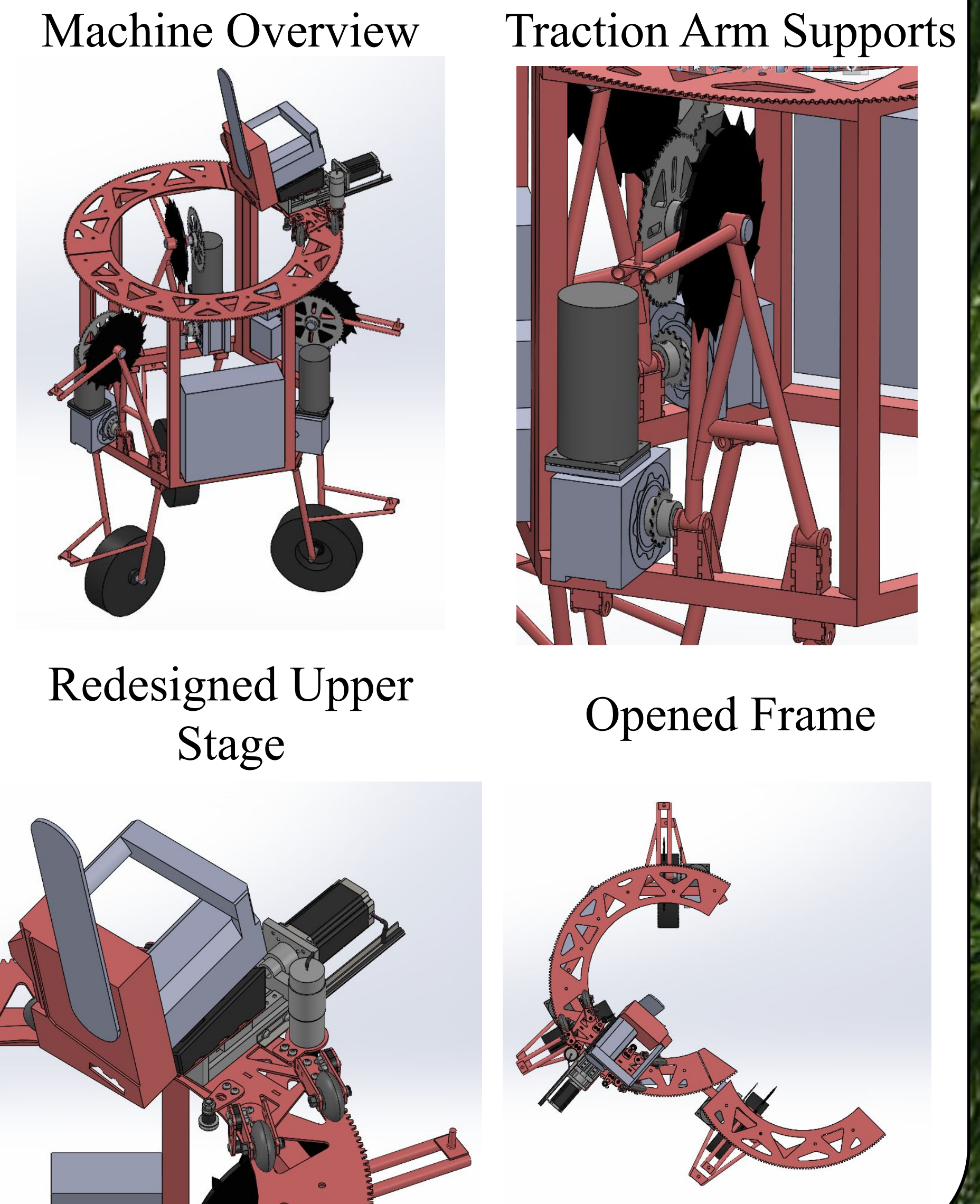
Wiring Diagram



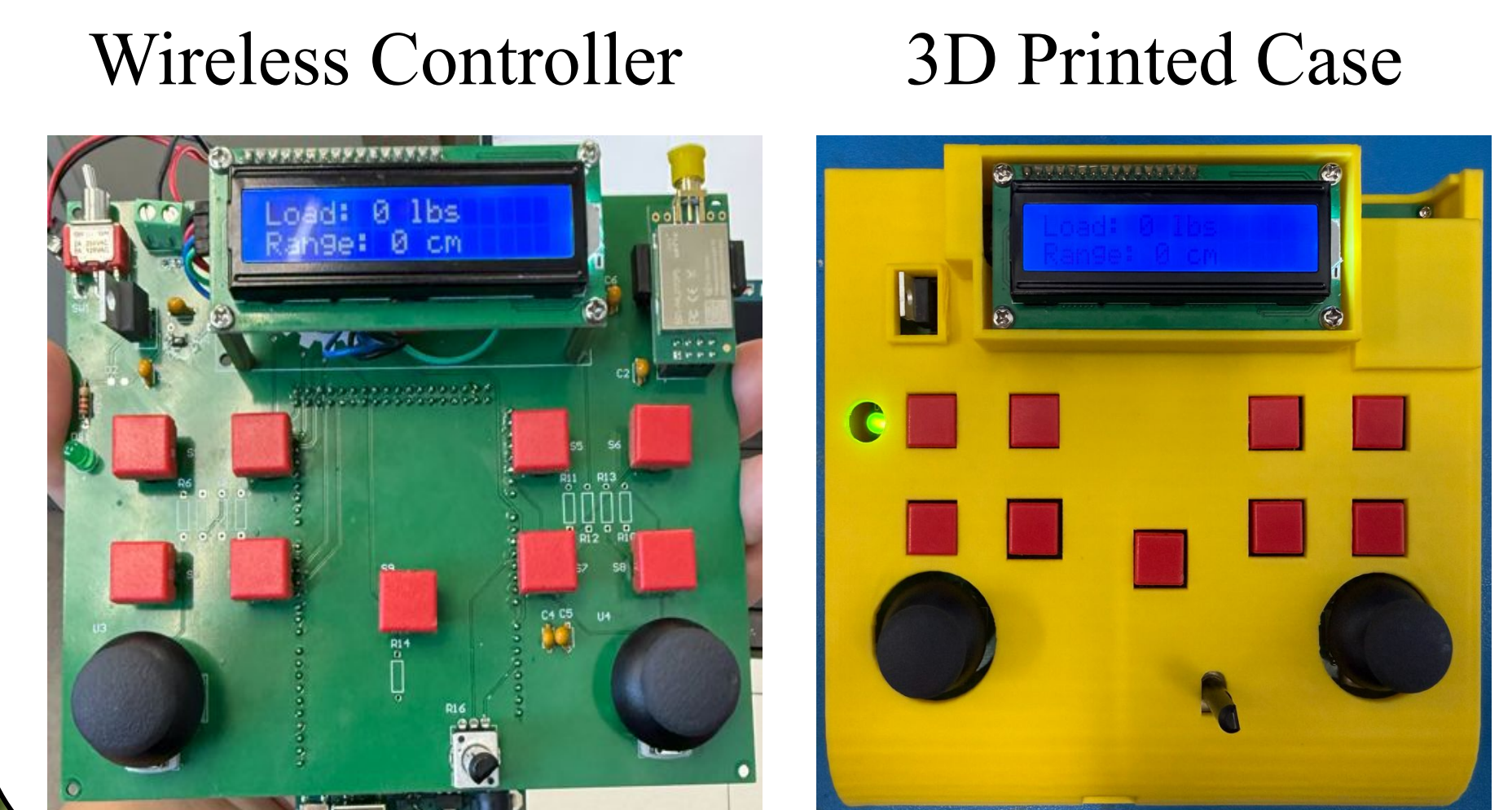
System Diagram



CAD Design



Controller



Acknowledgments

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